

• Ejemplo 1.

0	0	0	0	0
0	0	1	1	0
0	0	1	1	0
0	0	0	0	0
0	0	0	0	0

0,0	0,1	0,2	0,3	0,4
1,0	1,1	1,2	1,3	1,4
2,0	2,1	2,2	2,3	2,4
3,0	3,1	3,2	3,3	3,4
4,0	4,1	4,2	3,4	4,4

$$M_{pq} = \sum_x \sum_y x^p y^q f(x, y)$$

Para $p, q = 0, 1$

$$M_{pq} = \begin{bmatrix} M_{00} & M_{10} \\ M_{01} & M_{11} \end{bmatrix} = \begin{bmatrix} 4 & 10 \\ 6 & 15 \end{bmatrix}$$

$$M_{00} = \sum_x \sum_y f(x, y) = (1) + (1) + (1) + (1) = 4$$

$$M_{10} = \sum_x \sum_y x f(x, y) = (2)(1) + (3)(1) + (2)(1) + (3)(1) = 10$$

$$M_{01} = \sum_x \sum_y y f(x, y) = (1)(1) + (2)(1) + (1)(1) + (2)(1) = 6$$

$$M_{11} = \sum_x \sum_y x y f(x, y) = \underbrace{(2)(1)}_2 (1) + \underbrace{(3)(1)}_3 (1) + \underbrace{(2)(2)}_4 (1) + \underbrace{(3)(2)}_6 (1) = 15$$

• Ejemplo 2.

0	0	0	0	0
0	0	1	1	0
0	0	1	1	0
0	0	0	0	0
0	0	0	0	0

0,0	0,1	0,2	0,3	0,4
1,0	1,1	1,2	1,3	1,4
2,0	2,1	2,2	2,3	2,4
3,0	3,1	3,2	3,3	3,4
4,0	4,1	4,2	3,4	4,4

$$\mu_{00} = M_{00},$$

$$\mu_{01} = 0,$$

$$\mu_{10} = 0,$$

$$\mu_{11} = M_{11} - \bar{x}M_{01} = M_{11} - \bar{y}M_{10}$$

$$\mu_{pq} = \sum_x \sum_y (x - x_c)^p (y - y_c)^q f(x, y)$$

$$\mu = \begin{bmatrix} \mu_{00} & \mu_{10} \\ \mu_{01} & \mu_{11} \end{bmatrix} = \begin{bmatrix} 4 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\text{Centroide } \{\bar{x}, \bar{y}\} = \left\{ \frac{M_{10}}{M_{00}}, \frac{M_{01}}{M_{00}} \right\} = \left\{ \frac{10}{4}, \frac{6}{4} \right\} = 2.5, 1.5$$

Para p,q = 0,1

$$\mu_{00} = \sum_x \sum_y f(x, y) = 4 \quad (-0.5)(1) + (0.5)(1) + (-0.5)(1) + (0.5)(1)$$

$$\mu_{10} = \sum_x \sum_y (x - x_c)^1 f(x, y) = (2 - 2.5)(1) + (3 - 2.5)(1) + (2 - 2.5)(1) + (3 - 2.5)(1) = 0$$

$$\mu_{01} = \sum_x \sum_y (y - y_c)^1 f(x, y) = (-0.5)(1) + (0.5)(1) + (-0.5)(1) + (0.5)(1) = 0$$

$$\mu_{11} =$$

$$\begin{aligned} \sum_x \sum_y (x - x_c)^1 (y - y_c)^1 f(x, y) &= (2 - 2.5)(1 - 1.5)(1) + \\ &+ (3 - 2.5)(1 - 1.5)(1) + \\ &+ (2 - 2.5)(2 - 1.5)(1) + \\ &+ (3 - 2.5)(2 - 1.5)(1) = 0.25 - 0.25 - 0.25 + 0.25 = 0 \end{aligned}$$

Ejemplo 4.

- $D=1$, $\theta = 0$ (de izquierda a derecha)

La imagen:



```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

Pixel vecino ->	0	1	2	3
Pixel de referencia ↓				
0	2	2	1	0
1	0	2	0	0
2	0	0	3	1
3	0	0	0	1

$(0,0)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 2$

$(0,1)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 2$

$(0,2)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 1$

$(0,3)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 0$

$(1,0)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 0$

$(1,1)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 2$

$(1,2)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 0$

$(1,3)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 0$

$(2,0)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 0$

$(2,1)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 0$

$(2,2)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 3$

$(2,3)$

```

0 0 1 1
0 0 1 1
0 2 2 2
2 2 3 3
    
```

$= 1$

$(3, 0)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 0$

$(3, 1)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 0$

$(3, 2)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 0$

$(3, 3)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 3$

- Pero conviene que la matriz sea simétrica respecto a su diagonal principal.

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

Pixel vecino ->	0	1	2	3
Pixel de referencia ↓				
0	2	0	0	0
1	2	2	0	0
2	1	0	3	0
3	0	0	1	1

$(0, 0)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$=$

$(0, 1)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 0$

$(0, 2)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 0$

$(0, 3)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 0$

$(1, 0)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 2$

$(1, 1)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 2$

$(1, 2)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 0$

$(1, 3)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

$= 0$

(2, 0)

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

= 1

(2, 1)

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

= 0

(2, 2)

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

= 3

(2, 3)

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

= 0

(3, 0)

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

= 0

(3, 1)

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

= 0

(3, 2)

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

= 1

(3, 3)

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

= 1